

# RCP8™ Specifications

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## RCP8™ I/O Characteristics

<b>Expandable I/O</b>	SIGMET I/O-62 PCI card (one standard) with RCP8™ rackmount panel
<b>AZ and EL Angle Inputs</b>	TTL 16-bit binary of BCD for AZ and EL or Synchro/Resolver (various frequencies supported)
<b>AZ and EL Angle Outputs</b>	Parallel TTL Binary angle up to 16 bits, or serial RS232 Asynch
<b>Tach Inputs</b>	Analog up to $\pm 80$ V
<b>Antenna Drive Output</b>	+ 10 V to servo amplifiers for AZ and EL
<b>Status Bit Input Range</b>	Switch closure or wide range $\pm 27$ V triggering at +2.5V. 330K input impedance. +5V pull-up/down configurable by software
<b>Control Bit Output Range</b>	RS422 and TTL. In addition 6 DIP relays are provided for switch closure output
<b>A/D Inputs</b>	20 A/D inputs nominal $\pm 6$ V, 12 bits @ 100 Hz
<b>Host Interface</b>	10/100/1000T Ethernet or RS232C asynch serial selectable to 39 Kbps

## Antenna Control/Monitoring Features

<b>Servo Types</b>	Digital position and velocity servos for both AZ and EL (independent)
<b>Tachometer</b>	Analog TACH or "Virtual Tach" from differentiated angle input
<b>Velocity Servo Accuracy</b>	0.5% at 3 RPM typical
<b>Position Accuracy</b>	0.1 degrees typical
<b>Fail Safe Checks</b>	Soft limiting, out-of-bound elevation request limiting, out of bound elevation, limit switch diode clamping, limit switch shutdown, out of bound antenna speed, unresponsive antenna, tach and angle changes inconsistent, "dead" host computer

<b>Display</b>	Front panel 2-line user configurable display to show AZ and EL positions and velocities as well as status parameters and faults. Optional keyboard, mouse and monitor
<b>Radar Control/Monitoring Features</b>	
<b>Dedicated Control Outputs</b>	Servo Power, Radiate, T/R Power, Pulse Width (4), Reset Signal
<b>Dedicated Status Inputs</b>	Servo Power, Radiate, Standby, Wave Guide Pressure, Interlock, Cooling Airflow, Pulse Width (4), Antenna Local Mode
<b>Arbitrary BITE Monitoring and Control Features</b>	
<b>BITE Status/Control Outputs</b>	Up to 80 lines configurable in groups of 8 to be either input or output, TTL/CMOS
<b>Moving Platform Option</b>	
<b>Motion Reference</b>	Honeywell or Seatec INU with GPS update and serial output
<b>Physical and Environmental</b>	
<b>Packaging</b>	2U or 4U EIA 19" rackmount chassis. 3U rackmount connection panel
<b>Input Power</b>	85-264 VAC, 47-63 Hz
<b>Power Consumption</b>	70 Watts
<b>Environmental</b>	0°C to 50°C operating, 0 to 95% (non condensing) R.H.
<b>Reliability</b>	>50,000 Hours MTBF

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